Table of Contents

Ubiquitous and Cooperative Robots in Smart Space	
A Ubiquitous and Cooperative Service Framework for Network Robot System	1
Yabo Liu and Jianhua Yang	
The Hand-Bot, a Robot Design for Simultaneous Climbing and Manipulation	11
Francesco Mondada	
Human Multi-robots Interaction with High Virtual Reality Abstraction Level	23
Khelifa Baizid. Zhao Li, Nicolas Mollet, and Ryad Chellali	
Laser Based People Following Behaviour in an Emergency	
Environment	33
RENS - Enabling a Robot to Identify a Person Xin Yan, Sabina Jeschke, Amit Dubey, Marc Wilke, and Hinrich Schütze	43
Classifying 3D Human Motions by Mixing Fuzzy Gaussian Inference with Genetic Programming Mehdi Khoury and Honghai Liu	55
Pointing Gestures for a Robot Mediated Communication Interface John-John Cabibihan. Wing Chee So, Medi Nazar, and Shuzhi Sam Ge	67
View-Invariant Human Action Recognition Using Exemplar-Based Hidden Markov Models Xiaofei Ji and Honghai Liu	78
A Local Interaction Based Multi-robot Hunting Approach with Sensing and Modest Communication	90
Robot Formations for Area Coverage Jürgen Leitner	100



Table of Contents

Ubiquitous and Cooperative Robots in Smart Space	
A Ubiquitous and Cooperative Service Framework for Network Robot System	1
Yabo Liu and Jianhua Yang	
The Hand-Bot, a Robot Design for Simultaneous Climbing and	
Manipulation	11
Human Multi-robots Interaction with High Virtual Reality Abstraction	
Level	23
Laser Based People Following Behaviour in an Emergency	
Environment	33
RENS – Enabling a Robot to Identify a Person Xin Yan, Sabina Jeschke, Amit Dubey, Marc Wilke, and Hinrich Schütze	43
Classifying 3D Human Motions by Mixing Fuzzy Gaussian Inference with Genetic Programming Mchdi Khoury and Honghai Liu	55
Pointing Gestures for a Robot Mediated Communication Interface John-John Cabibihan, Wing Chee So, Medi Nazar, and Shuzhi Sam Ge	67
View-Invariant Human Action Recognition Using Exemplar-Based Hidden Markov Models Xiaofei Ji and Honghai Liu	78
A Local Interaction Based Multi-robot Hunting Approach with Sensing and Modest Communication Wenwen Zhang, Jing Wang, Zhiqiang Cao, Yuan Yuan, and Chao Zhou	90
Robot Formations for Area Coverage Jürgen Leitner	100

Advanced Control on Autonomous Vehicles

Challenges of the Multi-robot Team in the GUARDIANS Project Lyuba Alboul, Joan Saez-Pons, Jacques Penders, and Leo Nomdedeu	112
Modelling and Control of a Train of Autonomous Electric Vehicles Kamel Bouibed, Abdel Aitouche, and Mireille Bayart	126
Organization and Operation of Electronically Coupled Truck Platoons on German Motorways	135
Navigation Method Selector for an Autonomous Explorer Rover with a Markov Decision Process	147
Discrete-Time Adaptive Sliding Mode Control of Autonomous Underwater Vehicle in the Dive Plane Baoju Wu, Shuo Li, and Xiaohui Wang	157
Emergent Behavior Control Patterns in Robotic Collectives Razvan-Dorel Cioarga, Mihai V. Micea, Vladimir Cretu, and Daniel Racoceanu	165
Intelligent Vehicles: Perception for Safe Navigation	
Intelligent Vehicles: Perception for Safe Navigation An Improved Road Network Modeling and Map Matching for Precise Vehicle Localization Chenhao Wang, Zhencheng Hu, Naoko Hamada, and Keiichi Uchimura	174
Intelligent Vehicles: Perception for Safe Navigation An Improved Road Network Modeling and Map Matching for Precise Vehicle Localization Chenhao Wang, Zhencheng Hu, Naoko Hamada, and Keiichi Uchimura A Vision System of Hazard Cameras for Lunar Rover BH2 Guicai Wang, Hehua Ju, and Hongpeng Feng	174 185
Intelligent Vehicles: Perception for Safe Navigation An Improved Road Network Modeling and Map Matching for Precise Vehicle Localization Vehicle Localization Chenhao Wang, Zhencheng Hu, Naoko Hamada, and Keiichi Uchimura A Vision System of Hazard Cameras for Lunar Rover BH2 Guicai Wang, Hehua Ju, and Hongpeng Feng Stereovision-Based Algorithm for Obstacle Avoidance Lazaros Nalpantidis, Ioannis Kostavelis, and Antonios Gasteratos	174 185 195
 Intelligent Vehicles: Perception for Safe Navigation An Improved Road Network Modeling and Map Matching for Precise Vehicle Localization	174 185 195 205
 Intelligent Vehicles: Perception for Safe Navigation An Improved Road Network Modeling and Map Matching for Precise Vehicle Localization	174 185 195 205

Takahiro Wada, Shoji Hiraoka, and Shun'ichi Doi

Toward Preventive ACC Systems against Crashes Due to Another Vehicle's Cut-in	226
How Do Cognitive Distraction Affect Driver Intent of Changing Lanes?	235
Effects of Missed Alarms on Driver's Response to a Collision Warning System According to Alarm Timings Genya Abe, Makoto Itoh, and Tomohiro Yamamura	245
SLAM Estimation in Dynamic Outdoor Environments: A Review Zheyuan Lu, Zhencheng Hu, and Keiichi Uchimura	255
Robot and Automation in Tunneling (973)	
On the Analysis of Force Transmission Performance for the Thrust	

Systems of Shield Tunneling Machines	268
Passive Ultrasonic RFID Localization for Pipeline Pigs Xubing Chen, Hanxin Chen, and Youlun Xiong	279
Allocation of Measurement Error of Shield's Pose Minghua Pan, Bin Zhao, and Guoli Zhu	288
The Compliance Design on Thrust System of Shields Excavating in Various Geologic Conditions Zhongpo Liu, Genliang Chen, Haidong Yu, and Xinmin Lai	297
Analysis for Dynamic Load Behavior of Shield Thrust System Considering Variable Boundary Constraints Kaizhi Zhang, Haidong Yu, Zhongpo Liu, and Xinmin Lai	307
Evaluation and Optimization Method of High Speed Cutting Parameters Based on Cutting Process Simulation Zhijun Wu, Daochun Xu, Pingfa Feng, Dingwen Yu, and Chenglong Zhang	317
The Reconfiguration Design of Redundant Thrust of Shields Excavating in Various Geologic Conditions	326
Research of an Electric Laser System Based on the Non-diffracting Beam Hui Chen and Bin Zhao	336

15
65
54
74
33
€2
)2
12
23
33
13
53
53

Redundantly Actuated PRPRP Radial Mechanism in Segment Erector of Shield Machine for Synchronization Control Wanghui Bu, Zhenyu Liu, and Jianrong Tan	474
Electrohydraulic Control of Thrust Hydraulic System for Shield Tunneling Machine Beidou Zhu, Guofang Gong, and Hu Shi	482
Simulation Analysis of Pressure Regulation of Hydraulic Thrust System on a Shield Tunneling Machine	493

Robot Mechanism and Design

Variable Rheological Joints Using an Artificial Muscle Soft Actuator and Magneto-Rheological Fluids Brake	504
A Dexterous and Self-adaptive Humanoid Robot Hand: Gesture-Changeable Under-Actuated Hand Wenzeng Zhang, Demeng Che, Qiang Chen, and Dong Du	515
Design of the Upper Limb Rehabilitation Support Device Using a Pneumatic Cylinder Koichi Kirihara, Norihiko Saga, and Naoki Saito	526
Spike: A Six Legged Cube Style Robot Christopher Coyte, Mark Beckerleg, and John Collins	535
The Similarity Design of Heavy Forging Robot Grippers Qunning Li, Yonghong Wu, and Hua Deng	545
The Research of Mechanism Synthesis Based on Mechanical System Chaos Anti-control Methods	554

Robot Motion Analysis

A Method of Stiffness Analysis of Parallel Mechanisms Boqiang Xu, Tiemin Li, and Jun Wu	562
Numerical Methods for Frictional Contact of Multi-rigid-body with Redundant Constraints	571
Inverse Dynamic Modeling of Two Unsymmetrical 3UPU Parallel Manipulators Bo Hu, Yi Lu, and Haixia Mao	580

Kinematic Analysis of the SPKM165, a 5-Axis Serial-Parallel Kinematic	
Fugui Xie, Xinjun Liu, Jinsong Wang, and Liping Wang	
Kinematics Model of Bionic Wheel-Legged Lunar Rover and Its Simulation Analysis	
Dynamics and GA-Based Optimization of Rectilinear Snake Robot Ahmad Ghanbari, Mir Masoud Seyyed Fakhrabadi, and Ali Rostami	
Optimum Dynamic Modeling of a Wall Climbing Robot for Ship Rust Removal	1
Stiffness and Singularity Analysis of 2SPS+2RPS Parallel Manipulator by Using Different Methods Bo Hu, Yi Lu, and Jiayin Xu	1
A Simulation Model to Evaluate and Verify Functions of Autonomous Vehicle Based on Simulink [®] Jie Zhou, Hui Chen, and Caijing Xiu	(
Experimental Evaluation on Dynamic Characteristics of Coaxial Magnetic Couplings for Vacuum Robot Jun Wu, Pinkuan Liu, and Yulin Wang	(
Complex Surface Machining: Thermo-mechanical Analysis for Error Prediction of Low-Rigidity Workpiece	(
Modeling and Optimization of Contact Forces for Heavy Duty Robot Grippers Qunming Li, Dan Gao, and Hua Deng	(
Performance of Inertia Force Analysis for Spherical Bearing Test Stand Mechanism	(
Reordering and Partitioning Jacobian Matrices Using Graph-Spectral Method Xuelin Wang and Yujin Hu	(
Workspace Analysis and Parameter Optimization of a Six DOF 6-3-3 Parallel Link Machine Tool Minghui Zhang and Baohai Zhuo	7

Robot Motion Control

Keeping a Stable Position of Walking Robot with Vibration Grigory Panovko, Evgeniya Myalo, and Teodor Akinfiev	713
An Algebraic Approach for Accurate Motion Control of Humanoid Robot Joints Jorge Villagra and Carlos Balaguer	723
Modeling and Impedance Control of a Chewing Robot with a 6RSS Parallel Mechanism L. Huang, W.L. Xu, J. Torrance, and J.E. Bronlund	733
Decentralized Control for Swarm Flocking in 3D Space Xiang Li, M. Fikret Ercan, and Yu Fai Fung	744
Nonlinear Analysis and Application of Servo Control System Based on Relay Feedback Donglin Pu, Jianhua Wu, Zhenhua Xiong, Xinjun Sheng, and Han Ding	755
Kalman Estimator-Based State-Feedback High-Precision Positioning Control for a Micro-scale Air-Bearing Stage ZeGuang Dong, PinKuan Liu, and Han Ding	765
Dynamic Control and Analysis of a Nonholonomic Mobile Modular Robot Jingquo Wang and Yangmin Li	776

Visual Perception by Robots

Quantitative and Qualitative Evaluation of Vision-Based Teleoperation of a Mobile Robot Luca Brayda, Jesús Ortiz, Nicolas Mollet, Ryad Chellali, and Jean-Guy Fontaine	792
An Embedded Vision System for a Power Transmission Line Inspection Robot	802
What Visual Cues Do We Use to Perceive Depth in Virtual Environments?	812
Combination of Annealing Particle Filter and Belief Propagation for 3D Upper Body Tracking Ilaria Renna, Catherine Achard, and Ryad Chellali	824

Stereo Vision Based Floor Plane Extraction and Camera Pose Estimation	834
Lei Chen, Zhongli Wang, and Yunde Jia	001
Autonomous Mapping Using a Flexible Region Map for Novelty Detection	846
A Fast Connected-Component Labeling Algorithm for Robot Vision Based on Prior Knowledge Jun Liu, Guang Lu, Binbin Tao, Fang Chen, Haitao Gao, and Zhisheng Zhang	856
Simultaneous Visual Object Recognition and Position Estimation Using SIFT	866
Active Contour Method with Separate Global Translation and Local Deformation Linlin Zhu, Baojie Fan, and Yandong Tang	876
Automatic Soldering System Based on Computer Vision Zhenhua Xiong, Xinjue Zhou, Yulin Wang, and Han Ding	885
PLG-Based Visual Tracing for Eye-in-Hand Puma 560 Robot Wen-qiang Hu, Kai Tian, and Rong-Lei Sun	897
Obtaining Reliable Depth Maps for Robotic Applications from a Quad-Camera System Lazaros Nalpantidis, Dimitrios Chrysostomou, and Antonios Gasteratos	906
Surface Reconstruction of Engine Intake Ports with Mixed Constraints	917
Binocular Based Moving Target Tracking for Mobile Robot Yingkui Du, Baojie Fan, Jianda Han, and Yandong Tang	929
Robust Calibration of a Color Structured Light System Using Color Correction	936
Close Range Inspection Using Novelty Detection Results Muhammad Fahmi Miskon and Andrew R. Russell	947
The Vision System of the ACROBOTER Project Rigas Kouskouridas, Nikolaos Kyriakoulis, Dimitrios Chrysostomou, Vasileios Belagiannis, Spyridon G. Mouroutsos, and Antonios Gasteratos	957

Prediction Surface Topography in Flank Milling Wei Hao and Xiao-Jin Wan	967
Computational Intelligence by Robots	
Cognition Dynamics: Time and Change Aspects in Quantitative Cognitics	976
Adaptive Cellular Automata Traffic System Model Based on Hybrid System Theory	994
Study on a Location Method for Bio-objects in Virtual Environment Based on Neural Network and Fuzzy Reasoning Hongjun Wang, Xiangjun Zou, Changyu Liu, Tianhu Liu, and Jiaxin Chen	1004
Planner9, a HTN Planner Distributed on Groups of Miniature Mobile Robots	1013
An Adaptive Rolling Path Planning Method for Planet Rover in Uncertain Environment Jinze Song, Bin Dai, Huihai Cui, Enzhong Shan, and Hangen He	1023
Planning and Control of Biped Walking along Curved Paths on Unknown and Uneven Terrain GuoQing Zhang, Ming Xie, Hang Yin, Lei Wang, and HeJin Yang	1032
Robot and Application	
Experimental Study on Alpine Skiing Turn Using Passive Skiing Robot	1044

Norihiko	Saga	and	Kengo	Kono	

Design and Application of High-Sensitivity Hexapod Robot	1051
P.S. Pa and C.M. Wu	
Charles on Mine Deserve Delect Contant	1005

Study on Mine Rescue Robot System	1065
Juan Wei and Hong-wei Ma	

A Hybrid FES Rehabilitation System Based on CPG and BCI	
Technology for Locomotion: A Preliminary Study	1073
Dingguo Zhang, Guangquan Liu, Gan Huan, Jianrong Liu, and	
Xiangyang Zhu	

Introduction to the Development of a Robotic Manipulator for Nursing Robot	100-
Guang Lu, Binbin Tao, Jun Liu, Fang Chen, Jinfei Shi, and Zhisheng Zhang	1085
On the Design of Exoskeleton Rehabilitation Robot with Ergonomic Shoulder Actuation Mechanism Wenbin Chen, Caihua Xiong, Ronglei Sun, and Xiaolin Huang	1097
A Novel Five Wheeled Rover for All Terrain Navigation Arun Kumar Singh, Arun H. Patil, and Anup Kumar Saha	1111
A Study on Wafer-Handling Robot with Coaxial Twin-Shaft Magnetic Fluid Seals	1123
A Study on the Key Technology of Autonomous Underwater Vehicle–AUV's Self Rescue Beaconing System Guohua Xu, Kun Yu, and Xiaoliang Chen	1138
The Research on Mechanism, Kinematics and Experiment of 220kv Double-Circuit Transmission Line Inspection Robot Cheng Li, Gongping Wu, and Heng Cao	1146
The Design of the GPS-Based Surveying Robot Automatic Monitoring System for Underground Mining Safety Chenguang Jiang, Jianguo Peng, Chunqiao Yuan, Guohui Wang, Yong He, Shaohong Li, and Bo Liu	1156
Robot and Investigation	
Acquisition of Movement Pattern by Q-Learning in Peristaltic Crawling Robot Norihiko Saga and Atsumasa Ikeda	1163
The Study on Optimal Gait for Five-Legged Robot with Reinforcement Learning Adnan Rachmat Anom Besari, Ruzaidi Zamri, Anton Satria Prabuwono, and Son Kuswadi	1170
Study on External Load Domain of Shield Machine Cutterhead Weili Wen, Pingfa Feng, Zhijun Wu, and Jianhu Liu	1176

Obstacle-Climbing Capability Analysis of Six-Wheeled Rocker-Bogie	
Lunar Rover on Loose Soil	1183
Xiaoliu Yu, Yongming Wang, Meiling Wang, and Lifang Wang	

Optimal Design on Cutterhead Supporting Structure of Tunnel Boring Machine Based on Continuum Topology Optimization Method Zhen Li, Wei Sun, Junzhou Huo, Pengcheng Su, and Liying Deng	1190
The Flexible Two-Wheeled Self-balancing Robot Based on Hopfield Xian-gang Ruan and Jianwei Zhao	1196
Real-Time Simulation System of Virtual Picking Manipulator Based on Parametric Design	1205
Study of Modeling and Simulating for Picking Manipulator Based on Modelica Yan Chen, Shuang Jin, Xiang-jun Zou, Dong-fen Xu, and Wei-liang Cai	1211
Automatic Reconstruction of Unknown 3D Objects Based on the Limit Visual Surface and Trend Surface Xiaolong Zhou, Bingwei He, and Y.F. Li	1217
Hyper-chaotic Newton-Downhill Method and Its Application to Mechanism Forward Kinematics Analysis of Parallel Robot Youxin Luo	1224
Inverted Pendulum System Control by Using Modified Iterative Learning Control	1230
Dynamic Simulation of Passive Walker Based on Virtual Gravity Theory Heng Cao, Yu Wang, Jun Zhu, and Zhengyang Ling	1237
A New Strategy of the Robot Assembly Motion Planning Yanchun Xia, Yuehong Yin, Yuewei Bai, and Yafei He	1246
From Morphologies of Six-, Four- and Two-Legged Animals to the HexaQuaBip Robot's Reconfigurable Kinematics Alexandre Veinguertener, Thierry Hoinville, Olivier Bruncau, and Jean-Guy Fontaine	1255
Symbricator3D – A Distributed Simulation Environment for Modular Robots Lutz Winkler and Heinz Wörn	1266
Mono Landmark Localization for an Autonomous Navigation of a Cooperative Mobile Robot Formation Hugues Sert, Annemarie Kökösy, Jorge Palos, and Wilfrid Perruquetti	1278
Author Index	1293